# eMobility

# WAGO Leading the Charge



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# Six Steps to a Full Battery

## WAGO supports every aspect of charging from:



#### **Charging Process**

- Charging mode 3 according to IEC 61851-1
- Automatic connector lock
- Power measurement via 750-493 3-Phase Power Measurement Module
- Connecting standard billing meters via S0 bus acc. to DIN 43864 or SML

Power Optocoupler with S0 Interface, 286-740 3-Phase Power

Measurement Module, 750-493



SO Supply Module for Passive SO Current Meter Interfaces, **286-742** 

#### **Completion of Charging Process**

- SMS message via 761-510 TO-PASS® Modem
- Communication with external service providers and payment systems, such as prepaid cards



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TO-PASS<sup>®</sup> GPRS Modem, RS-232/VPN Router, **761-510** 

#### **Charging Station Controllers**

- Programmable via CoDeSys
- Internal Web server for visualization, multitasking and battery-backed, real-time clock
- Master/slave operation for use in main stations with satellites
- Both centralized and decentralized system architectures are possible
- Select WAGO-I/O-SYSTEM components are designed for an extended temperature range of -20°C to +60°C



Telecontroller, 750-872

> For additional information, please contact our specialists at: eMobility@wago.com

## WAGO Pilot-Box

### for charging mode 3 according to IEC 61851-1

#### Charging Mode 3

IEC 61851-1 distinguishes between four charging modes depending on the application. The most flexible, and therefore most extensive charging mode, is charging mode 3. The charging station assumes various tasks, which go beyond the "simple" supply of voltage. These tasks include detecting the rated power of the charging cable, monitoring the protective conductor connection, transmitting the maximum available charging current and detecting interruptions in the charging circuit. There is an exchange of information between the vehicle and charging station via pilot signals. The pilot signal is a PWM signal, which transmits corresponding charging conditions between the vehicle and charging station (bidirectional) by a change in the signal level and in the pulse-no-pulse ratio.

#### Standard Charging Cycle to EN 61851-1



- 1 The charging station is in standby. No electric vehicle is connected.
- 2 Connection between the charging station and electric vehicle is established (plug in the charging cable).
- 3 The charging station transmits the maximum available charging current via PWM signal to the vehicle.
- 4 Electric vehicle displays that is ready to charge (with or without ventilation).
- 5 The charging contactor closes. The supply voltage is connected to the vehicle.
- 6 Vehicle charges with the maximum available charging current (I<sub>mat</sub>).
- 7 The maximum available charging current is reduced by the energy provider. The vehicle adjusts the charging current to the PWM signal.
- 8 Battery is charged. The charging current is reduced.
- 9 Vehicle notifies the charging station that charging is complete.
- 10 The charging contactor drops away. The vehicle is disconnected from the power supply.
- 11 The charging process is completed by the charging station. The connector lock opens.
- 12 The connection between the charging station and vehicle is released (disconnect the charging cable).



#### **Charging Current Path Selection**

Pilot-Box determines the optimal charging path from the maximum available charging current and the current carrying capacity of the charging cable. The proximity signal of the charging cable is evaluated. The results are passed to the digital outputs Act\_Max\_Curr for further processing. The line protection / charging current path is then easy to select. In addition, this information can be further

processed in a superimposed charge control.

WAGD

Pilot-Box

Power

lugIn Detection/Charge



#### **Connector Lock**

Plugging and unplugging the charging cable assembly under load should be avoided whenever possible. Unplugging the assembly under load can damage the plug and coupling. To prevent this, the connector is automatically locked after plugging it in. The connector is unlocked after completing the charging process and released by the user. In the event of a power failure, the module unlocks independently via integrated energy buffer. This also allows the vehicle to be disconnected in the event of a power failure.

#### Technical Data

Operating voltage: Power consumption: Max. ambient operating temperature: Dimensions (W x H x D): Conductor termination: 12 - 24 VDC (±-10%) <2 W -30°C ... +75°C

54 mm x 62 mm x 90 mm MCS connector with CAGE CLAMP<sup>®</sup> 0.08 - 1.5 mm<sup>2</sup> (AWG 28-16) "s" + "f-st"

#### Adjusting the Charging Current

On the one hand, the maximum available charging current is determined by the spatial installation on site (cable cross section, circuit protection, accumulation of factors, etc.) and on the other, by the maximum capacity of the energy provider. To provide maximum flexibility to both, two digital inputs are available for configuration. The Smart Grid can then be used and the vehicle is charged based on the network capacity.

### **SMART GRID**

# Smart Grid – Intelligent Network for Smart Solutions



Smart Grid: Communication via IEC 60870-5-101/-104 and 61850/61400

# Flexible, distributed energy producers Combined heat **Biogas** plants Hydro power and power plant Modern, renewable energy producers Wind farms Solar farms • Energy storage facilities Consumers Pumped-storage Building with Cold store power plant heat pumps

 WAGO Kontakttechnik GmbH & Co. KG Postfach 28 80 · D - 32385 Minden Hansastraße 27 · D - 32423 Minden Germany
Phone: +49 571 887-0

France: +49 Fax: +49 E-mail: info Online: www

+49 571 887-0 +49 571 887-169 info@wago.com www.wago.com

