

### **Features**

- Based on AMR sensor technology
- Programmable to customer specifications
- Symmetric output option

### **Applications**

- AFLS (Advanced Front Lighting System)
- Dynamic headlamp leveling
- ECAS (Electronically Controlled Air Suspension)
- Active suspension

## **Non-Contacting Chassis Level Sensor**

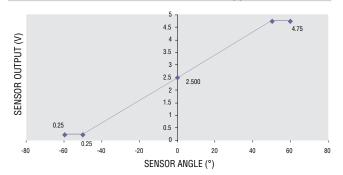
### Introduction

Bourns® Chassis Level Sensor is based on Anisotropic Magneto-resistance (AMR) sensor technology. The sensor arm or lever is attached to a magnet that is suspended above the MR sensor chip. The angular position of the sensor arm is measured and an output signal that is proportional to the angular orientation is generated. The output characteristic can be programmed to the customer specification. The output of the sensor can be programmed to be symmetric to allow the sensor to be mounted in all four suspension locations when used as a chassis level sensor or other applications.

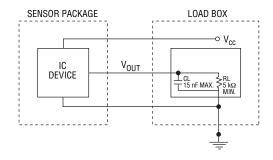
#### **Electrical Interface Specifications**

Operating Temperature	40 °C to +105 °C
	(up to +150 °C upon request)
Supply Voltage (V <sub>CC</sub> )	5 V ±10 %
Angular Sensing Range	+100 ° (typical)
Accuracy/Resolution	12 bit / 0.05 °
Electrical Range	
Mechanical Range	60 ° to +60 °
Temperature Range	40 to +105 °C
Update Rate	< 1 ms
Maximum Current Draw	12 mA
Maximum Output Current	2 mA
Operating Output Voltage Range.	0.05 V <sub>CC</sub> to 0.95 V <sub>CC</sub>
	$(0.25 \text{ to } 4.75 \text{ V } @ \text{V}_{CC} = 5 \text{ V})$
Sensitivity	0.45 mv / degree
(programma	able to customer requirements)
Total Error Band	< ±2.5 % (static pulse noise)
Variation from Zero Point	±2 °
Signal Output	Analog, PWM, SENT

### Typical Analog Output Characteristic (V<sub>CC</sub> = 5 V)



### **Three-Pin Interface**



### Automotive Division

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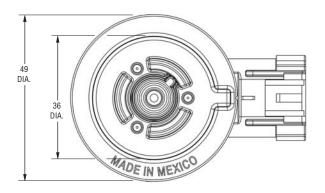
www.bourns.com

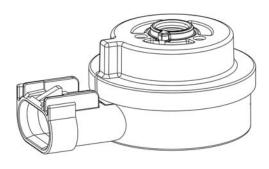
automotive@bourns.com

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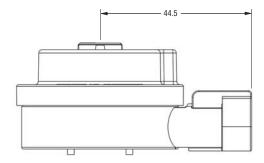
## BOURNS

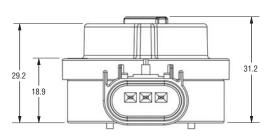
### **Design and Mechanical Interface**





DIMENSIONS: MM





### Connector Interface USCAR 150-S-003-1-B01

